**Week 16**

**TEAM MEETING**

***Cameron,*** *Diogo, Jose, Samuel, Yujui, Lio*

## Notes from meetings throughout the week

A few other notes from Wednesday’s meeting:

* We are no longer pursuing the non-holonomic option. Limits the options for demos and increases the complexity of controls. Couldn’t find a magnet combination that worked well either.
* Arms are not backdrivable with the weak magnets (the magnet coupling breaks too easily when moving quickly) so we’re going to go with admittance control the whole way. That means we can leave the gearboxes on.
* Main goal moving forward is to have a few really polished demos for the demo day when the time comes. This more than likely means that we’ll go with the one weak and one strong magnet configuration

Notes from Friday, Task list moving forward.

* Insert an E-stop button
* Add acrylic walls to protect sides, top and front
* Put electronics down to plate
* Finalize the calibration mode
* Tighten gear boxes
* Finalize arm links